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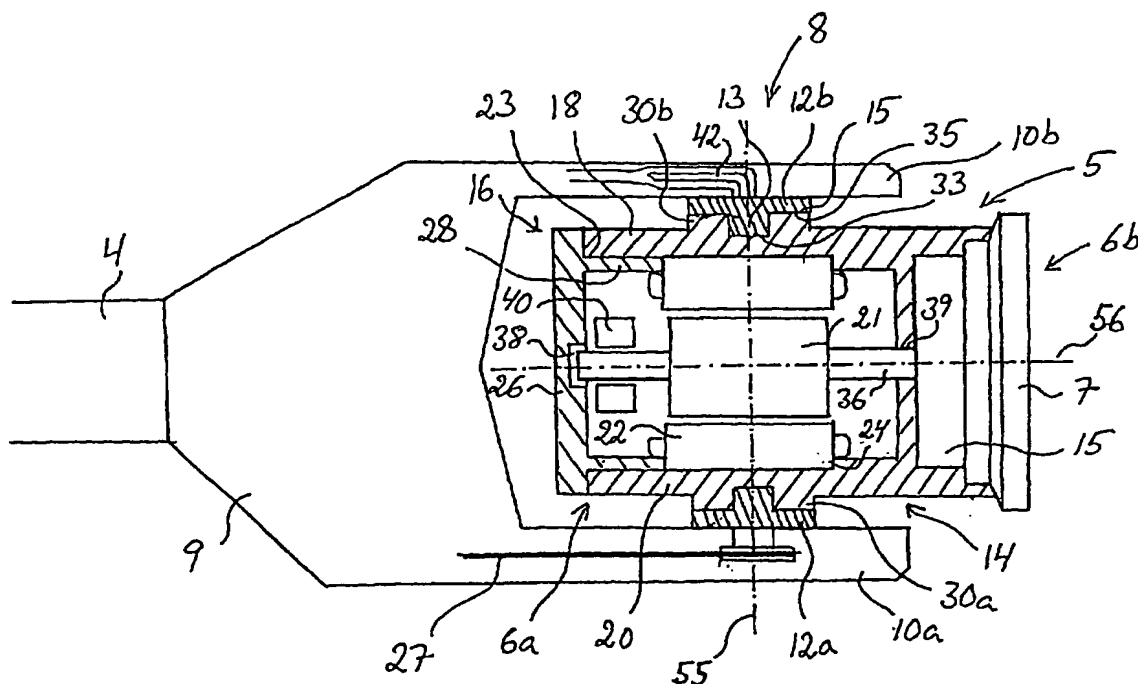
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(54) Title: A ROBOT WRIST COMPRISING A DRIVE UNIT INCORPORATED IN A TILT



(57) Abstract: A robot wrist for an industrial robot, wherein the robot wrist (8) comprises a wrist part (5), here designated tilt, mounted at a wrist housing (9) of the industrial robot. The tilt (5) is rotatable relative to the wrist housing (9) about an axis of rotation (55) and comprises a drive unit (14) that comprises a motor (16) with a motor housing (18).



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*For two-letter codes and other abbreviations, refer to the "Guidance Notes on Codes and Abbreviations" appearing at the beginning of each regular issue of the PCT Gazette.*